APPENDIX

Table 1. J1 Definition, Thermistors & Personality Pins

Connector	Pin	Mode	Type / Load	Function
J1	1	Input	Analog 0-5V	Thermistor Input [FF1]
J1	2	Input .	Analog 0-5V	Thermistor Input [FF2]
J1	3	Input -	Analog 0-5V	Thermistor Input [FZ]
J1	4	Input .	Analog 0-5V	Thermistor Input [EVAP]
J1	5	Input	Analog 0-5V	Thermistor Input [Pan]
J1	6	Input	Digital 0-5V	Personality Input
J1	7	Input	Digital 0-5V	Personality Input
J1	8	Output	5V Power supply	Reference for Thermistors
J1	9	NC	NC	NC

Table 2. J2 Definition, Fan Control

Connector	Pin	Mode	Type / Load	Function
J2	1	Input	Digital 0-12V	RPM Input (Evap)
J2	2	Input	Digital 0-12V	RPM Input [Cond]
J2	3	Power	Digital 0V – Hi Z / 850 mA	Motor Common [Evap & Cond]
<b>J</b> 2	4	Output	Analog 0-12V / 425 mA	Fan Drive Voltage [Evap]
J2	5	Output	Analog 0-12V / 425 mA	Fan Drive Voltage [Cond]
<b>J</b> 2	6.	Output	Digital 0V – Hi Z /200 mA	Low Active Fan Ouptut [FF]
J2	7	Output	Digital 0V – Hi Z / 200 mA	Low Active Fan Ouptut [Pan]
<b>J</b> 2	8	Power	12V Power supply / 400 mA	Power For Low Active Fans [FF & Pan]

Table 3. J3 Definition, Encoders and Mullion Damper

Connector	Pin	Mode	Type / Load	Function
J3	1	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 2)
J3	2	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity

Λ\_1

Table 3. continued

Connector	Pin	Mode	Type / Load	Function
				of pin 1)
J3	3	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 4)
J3	4	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 3)
J3	5	Input	Digital 0-5V	Encoder Drive
J3	6	Input	Digital 0-5V	Encoder Drive
<b>J</b> 3	7	Output	Digital 0-5V	Encoder Input [Bit 3]
J3	8	Output	Digital 0-5V	Encoder Input [Bit 2]
J3	9	Output	Digital 0-5V	Encoder Input [Bit 1]
J3	10	Output	Digital 0-5V	Encoder Input [Bit 0]

Table 4. J4 Definition, Communications

Connector	Pin	Mode	Type / Load	Function
J4	1	Input / Output	Digital 0-5V	Serial Communication Stream
J4	2	Output	12V Power supply / 1.25 A	Power for Temperature Control and Dispenser Boards
J4	3	Output	DC Common / 1.25 A	DC Common (Not connected to earth ground)
J4	4	Input	Digital 0-12V	Dumb Dispenser Status Input
J4	5	Input	Digital 0-12V	Dumb Dispenser Status Input

Table 5. J5 Definition, Pan Damper Control

Connector	Pin	Mode	Type	Function
J5	1	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 2
J5	2	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 1
J5	3	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 4
<b>J</b> 5	4	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 3

Table 6. J6 Definition, Flash Programming

Connector	Pin	Mode	Туре	Function
J6	1	Output	5 Volt Power Supply	Power Supply Output
J6	2	Output	DC Common	DC Common (Not connected to earth ground)
J6	3	Input	Digital 0-5V	Serial Data Received
J6	4	Output	Digital 0-5V	Serial Data Transmitted
J6	5	NC	NC	NC
J6	6	NC	NC	NC
<b>J</b> 6	7	Input	12 Volt Power Input	VFPP
J6	8	Input	Digital 0-5V	Test Pin
J6	9	Input	Digital 0-5V	P19
J6	10	Input	Digital 0-5V	Reset
J6	11	NC	NC	NC
J6	12	NC	NC	NC
J6	13	Output	DC Common	DC Common (Not connected to earth ground)
J6	14	Input	DC Common	DC Common to Select Programming Mode

Table 7. J7 Definition, AC Loads

. Connector	Pin	Mode	Type / Load	Function
J7	1	Output	117VAC Line / 4 A	Auger Drive Relay Connects to Pin 4 of This Connector
J7	2	Output	117VAC Line / 0.3 A	Crusher Drive
J7	3	Output	117VAC Line / 0.5 A	Water Valve Drive
J7	4	Input	117VAC Line / 4.3 A	Auger Drive Relay Connects to Pin 1 of This Connector
J7	5	Output	117VAC Line / 200 mA	Thaw Heater Power
J7	6	Input	117VAC Line	Fresh Food Door
J7	7	Input	117VAC Line	Freezer Door
J7	8	NC	NC	NC
J7	9	Input	117VAC Neutral	Return for Door Detection Circuits

### Table 8. J8 Definition, Compressor Run

Connector	Pin	Mode	Type / Load	Function
J8	1	Output	117VAC Line / 3	Compressor Run
			Α	Relay

#### Table 9. J9 Definition, Defrost

Connector	Pin	· Mode	Type / Load	Function
J9	1	Output	117VAC Line /	Defrost Run
		·	6.4 A	Relay

#### Table 10. J11 Definition, Line Input

Connector	Pin	Mode	Туре	Function
J11	1	Input	117VAC Line	Line Input

#### Table 11. J12 Definition, Pan Heater

Connector	Pin	Mode	Type	Function
J12	1	Output	117VAC Line /	Pan Heater
			0.5 A	Relay Output

#### **Table 12 Set Points Associated With Various LEDs**

PLATFORM	Leap Frog		BI	90	Quantum	
LED	Fresh	Freezer	Fresh	Freezer	Fresh	Freezer
	Food	(Degrees F)	Food	(Degrees F)	Food	(Degrees F)
	(Degrees F)		(Degrees F)		(Degrees F)	
0	Off	Off	Off	Off	Off	Off
1 - Warmest	45	6	46	6	45	6
2	40	4	41	4	40	4
3	39	3	39	3	39	3
4	38	1	38	1	38	1
5	37	0	37	0	37	0
6	36	-1	36	-1	36	-1
7	35	-3	. 35	-1	35	-3
8	35	-4	35	-4	35	_4
9- Coldest	34	-6	34	-6	34	-6

### Table 13 Diagnostic Key Sequences

FZ	FF	Mode	
Display	Display	Mode	Comments
0	1	HMI to Main Control Communications	The Turbo Cool LED will light up confirming communication between the two boards.
0	.2	HMI to Dispenser Communications	The Turbo Cool LED will light up confirming communication between the two boards.
0	3	Dispenser to Main Control Communications	The Turbo Cool LED will light up confirming communication between the two boards.
0	4	Encoder Test	As the encoders are rotated, the test mode will stop flashing and the corresponding setting of the encoder will appear on the freezer display of the HMI.
0	5	HMI Self Test	See below
0	6	Control and Sensor System Self Test	See below
0	7	Open Duct Door	Duct Door will open for 10 seconds and then close
0	8	Sweat Heater Test	Turn the sweat heater on for 60 seconds
0	9	Open Dampers	Each Damper will open, pause briefly, and then close
1	0	Fan Speed Test	Each fan will run for 30 seconds at low speed, then for 30 seconds at medium speed, and finally for 30 seconds at high speed.
1	1	100% Run Time	This mode runs the sealed system 100% of the time. This will automatically time out after 1 hour of run time.
1	2	Enter Prechill	This places the freezer in prechill mode. It will return to normal operation on its own.
1	3	Enter Defrost	This will set the refrigerator into defrost mode. It will return to normal operation on its own. If the cavity is not cold when this mode is executed, it may execute extremely fast.
1	4	Refrig	Causes a system reset.
1	5	Test Mode Exit	Causes a temperature board reset

				time.				
2	1 2 Enter Prechill This p		This pla	This places the freezer in prechill mode. It will				
				return t	n to normal operation on its own.			
No.	1	3	Enter Defrost		This will set the refrigerator into defrost mode. It			
	1 1				urn to normal operation on its own. If the			
44 143	1				s not cold when this mode is executed, it may			
					extremely fast.			
	1	4	Refrig	Causes	a system reset.			
	1	5	Test Mode Exit		a temperature board reset			
	-							
â:								
2								
21								
	-	[ab]e	14					
	Device							
<b>!</b>	ermistor		<u>Detection</u>		Strategy			
FZ 11H	ermistor	1	<ul> <li>FZ Thermistor Circuit OPEN</li> </ul>	Į.	<ul> <li>Set FZ unfiltered temp = -40, ensuring unigric</li> </ul>			
l		- 1			bottom row (X,W,V,U,T,S) execution.			
FF1 or	FF2 Thermist	or	FFx Thermistor Circuit OPEN		EFOSSO disabled.			
(Quant			TA TRAINISM OF CHE	IN.	Quantum only - Disregard out of range FFx temp. in the FF avg. temp. calculation.			
FF1 ar	d FF2 Thermi	stor	<ul> <li>FF1 Thermistor Circuit OPE</li> </ul>	N, AND	Set FF no freeze < FF avg. unfittered temp <			
themi	O, Leap single	FF	<ul> <li>FF2 Thermistor Circuit OPE</li> </ul>	N	low hysteresis, ensuring unigrid (E,K,Q,W)			
	er Operation		Damper commanded open		column execution.			
		1	<ul> <li>Damper commanded open, temperature increases &gt; 0.3</li> </ul>	but FF avg	<ul> <li>Send appropriate command again to damper</li> </ul>			
		1	<ul> <li>Damper commanded closed</li> </ul>	r Kiomin. I hit FF evo	(open/close)			
<u> </u>			temperature decreases > 0.3	3F in 5 min.				
Evap.	Thermistor		<ul> <li>Evap. Thermistor Circuit OP</li> </ul>	EN	Defrost operation occurs as follows: defrost			
		1			duration of 20 minutes, dwell duration of 5			
		1			minutes, and 8 hours of compressor run time			
Evap. (			No RPM feedback		elapses between defrosts.			
Power	Line Fault		• None		<ul> <li>Operate evaporator fan at 100% duty cycle.</li> <li>Store defrost state and defrost timer status ex</li> </ul>			
		l			30 minutes or upon defrost state change.			
		-			Algorithm uses saved state and timer values			
		1			FZ temp < Defrost termination temp.			
					<ul> <li>Algorithm reinitializes state and timer values i</li> </ul>			
		!-			FZ temp >= Defrost termination temp.			

Table /5 Control Board Commands

Add- ress	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x01	Firmware Version	<3 byte ascii version>	
0x10	0x61	Monogram Pan Heater Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x62	Feature Pan Damper 1 Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x63	Feature Pan Damper 2 Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x64	Feature Pan Heater Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x65	Damper Control		Open if Data =  0x51 and Close if  Data = 0x41

0x10

0x10

0x10

0x74

0x75

0x76

Start Compressor

**Energize Crusher** 

Bypass Solenoid

Read Sealed System

**ON Time** 

Table /5 continued Physical Response Command Received Communication Add-Com. Response ress Byte 0x41=Off, Start/Stop Condenser 0x10 0x66 0x51=On Fan 0x00=Off, Start/Stop Evaporator 0x10 0x67 0x01=Low, Fan (Variable Speed) 0x02=Med,0x03=High 0x00=Off,0x10 0x68 Start/Stop Fresh Food 0x01=Low,Fan (Variable Speed) 0x02=High Start If Data = 0x10 0x69 Start/Stop Turbo 0x51 and Stop If Mode Data = 0x41Chill Pan Fan 0x10 0x6A Start/Stop Feature Starts With Data Pan Fan (Variable Value Setting Speed) Speed Condenser Fan Speed 1 Bytes 0x10 0x6B 0x51=On, 0x41=Off Request 0x41=Logical 2 Bytes Evaporator Fan 0x10 0x6C State, 0x51=RPM For Logical: 0=Off, Speed Request i=Low, 2=Med, 3=High 0x6D Fresh Food Fan 1 Byte 0x10 0=Off, 1=Low, Speed Request 2=High Feature Pan Fan 1 Byte 0x6E 0x10 0x51=On, 0x41=Off Speed Request One Data Byte with 0x10 0x70 Dispense masks for each selection Water = 0x01Cubed =0x02Crushed = 0x04Engage If Data = 0x10 0x71 Engage Water Valve 0x51 and Release If Data = 0x41Energize If Data = 0x10 0x72 **Energize Defrost** 0x51 and Release Heater If Data = 0x41Energize If Data = 0x10 0x73 Energize Auger 0x51 and Release Motor If Data = 0x41

2 Bytes < Minutes of

ON Time>

Start If Data =

0x51 and Stop If
Data = 0x41
Energize If Data =

0x51 and Release

If Data = 0x41

# Table/5 continued

		lable/5 Willined		
Add- ress	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x77	Read Sealed System OFF Time	2 Bytes <minutes of<br="">OFF Time&gt;</minutes>	
0x10	0x80	Read FF Thermistor l	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61=Unamp. 0x71=A/D Counts
0x10	0x81	Read FF Thermistor 2	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61=Unamp. 0x71=A/D Counts
0x10	0x82	Read FZ Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61=Unamp. 0x71=A/D Counts
0x10	0x83	Read Evaporator Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61=Unamp. 0x71=A/D Counts
0x10	0x84	Read Feature Pan Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61=Unamp. 0x71=A/D Counts
0x10	0x85	Read Ambient Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x71=A/D Counts
0x10	0x86	Get Number of Door Openings	4 Bytes: FZ MSB, FZ LSB, FF MSB, FF LSB	
0x10	0x87	Reset Door Openings Counter		
0x10	Ox88	Read Sensors	<pre><state -="" of="" sensors="" various=""> 1 byte&gt;</state></pre>	
0x10	0x89	Read Dispense Counters	6 Bytes: Water MSB, Water LSB, Cubed MSB, Cubed LSB, Crushed MSB, Crushed LSB	
0x10	0x8A	Enter Peature Pan Defrost Mode		0 = Off 1 = Small Pkg. 2 = Med. Pkg. 3 = Lg. Pkg.
0x10	0x8B	Enter Feature Pan Quick Chill Mode		0 = Off 1 = 15 min. 2 = 30 min. 3 = 45 min.
0x10	0x8C	Reset Dispense Counters		-
0x10	0x90	Reset Freshness Filter Timer		
0x10	0x91	Reset Water Filter Timer		

0x10

0xB5

Status of Outputs

#### Table /5 continued Add-Com. Command Received Communication Physical Response Byte ress Response 0x10 0xA0 Set EEPROM Read Memory pointer is Address set for next Diagnostic eeprom read sequence. 0x10 0xA1 Set EEPROM Read Memory read Length length is set for next Diagnostic eeprom read sequence. 0x10 0xA2 Read EEPROM <EEPROM Data defined by previous two commands> 0x10 0xA3 Write EEPROM First two data bytes define the eeprom address, bytes three and four are the data written to that 16 bit area. 0x10 0xA4 Read Set Points <Set Point Temperatures from EEPROM (First Byte is FF, Second Byte is FZ)> 0x10 0xA5 Write Set Points Send Set Points to EEPROM (First Byte is FF, Second Byte is FZ) 0x10 0xB0Check Refrigerator <State of Status Refrigerator> 0x10 0xB1 Perform FF Fan 1 = Fan OK Diagnostics 2 = Fan Missing orOpen 3 = Fan Shorted 4 = Fan Stalled 0x10 0xB2 Perform Evap Fan 1 = Fan OK **Diagnostics** 2 = Fan Missing or Open 3 = Fan Shorted 4 = Fan Stalled 5 = Blade Missing 0x10 0xB3 Perform Cond Fan 1 = Fan OK **Diagnostics** 2 = Fan Missing or Open 3 = Fan Shorted4 = Fan Stalled 0x10 0xB4 Perform Feature Fan 1 = Fan OK Diagnostics 2 = Fan Missing or

Open
3 = Fan Shorted
4 = Fan Stalled

2 Bytes <Status of digital I/O>

Add- ress	Com.  Byte	Command Received	Communication Response	Physical Response
0x10	0xBA	Get Encoder Settings	2 Bytes: FF Setting, FZ Setting	
0x10	0xBC	Get Model Inputs	1 Byte with value of model inputs	
0x10	0xC0	Enter Diagnostic Mode		All outputs are off or closed
0x10	0xC1	Exit Diagnostic Mode		Will reset refrigerator
0x10	0xF9	Forced Reset		
0x10	0xFA	Forced Prechill		
0x10	0xFB	Forced Defrost		
0x10	0xFC	100% Run		
0x10	0xFD	Disable defrost		
0x10	0xFE	Calibrate thermistor channels against known resistance		

# Table 16

Bit 128	Bit 64	Bit 32	Bit 16	Bit 4	Bit 2	Bit 2	Bit 1
0	0	FF Door	FZ Door	0	0	0	0

D-4-	D:47	l Bir	D: 6	1 50. 4	D:: 0	1 5: 6	1 50. 2	T
Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	FF	FZ	Water	Auger	State	Crush	Mongr.	Defrst
	Door	Door	Disp.	State	of	Sol.	Heater	Heatr
	Sensr	Sensr	Valve		Com-	State	ļ	State
			State		press			
1	Damp.	Feat.	Feat.	Feat.	Feat.	Cond	FF Fan	0
1	State	Pan	Pan	Pan	Pan	Fan		
1		Damp.	Damp.	Heatr.	Fan			
		1 State	2 State		ļ			
2	FF1 Ten	ıp MSB		•	<del></del>	<del></del>		•
3	FF1 Ten	ip LSB						
4	FF2 Ten	ap MSB						
5	FF2 Ten	ap LSB						
6	FF Aver	age Temp	MSB					
7	FF Aver	age Temp	LSB					
8	FZ Tem	MSB						
9	FZ Tem	LSB					-	
10	Evap Te	mp MSB						
11	Evap Te	Evap Temp LSB						
12	Feature 1	Pan Temp	MSB					
13	Feature Pan Temp LSB							
14	Evap Fa	n Speed (0	=Off, 1=L	ow, 2=Me	xd, 3=High	1)		

	ta	bie /o		
Add- Ress	Com. Byte	Command Received	Communication Response	Physical Response
0x11	0x01	Firmware Version	<3 byte ascii version>	
0x11	0x6F	EEPROM data from mainboard		
Ox11	0x90	Set Display		See table below
0x11	0x91	Read Buttons	<state -="" buttons="" of="" various=""> 4 bytes&gt;</state>	
0x11	0x92	Pulse Beeper		
0x11	0xA4	Reply from main with temperature settings		
0x11	0xBA	Reply from main with encoder settings		
0x11	0xC0	Door Open		0x51 = door open 0x41 = door closed
Ox11	0xF2	Temperature to main/dispenser communications test		
0x11	0xF3	Dispenser to main communications test		
0x11	0xF4	Open duct door		
0x11	0xF5	Sweat heater test		
0x11	0xF6	Sensor system self- test		
0x11	0xF9	Forced reset		

Table /9

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	Thaw 1	Cool	Lock	Filter	Door	Cube	Crush	Water
1	0	0	0	Chill 3	Chill 2	Chill 1	Thaw 3	Thaw 2
2	Bits 0 -	6 , Fresh I	Food LED	0				
3	Bits 0 -	6, Fresh I	Food LED	1			•	
4	Bits 0 -	6, Fresh I	Good LED	2		-		
5	Bits 0 -	6, Freeze	LED 0					
6	Bits 0 – 6, Freezer LED 1							
7	Bits 0 – 6, Freezer LED 2							

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Lock	Reset Fresh Filter	Fresh Food Dec	Fresh Food Inc	Freezer Dec	Freezer Inc	Defrost / Chill	Turbo Cool
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	Door	Thaw	Light	Cube Key	Water Key	Crush Key

	IONIC	· ~		
Add- Ress	Com. Byte	Command Received	Communication Response	Physical Response
0x12	0x01	Firmware Version	<3 byte ascii version>	
0x12	0x6F	EEPROM data from mainboard		
0x12	0x90	Set Display		See table below
0x12	0x91	Read Buttons	<pre><state -="" buttons="" of="" various=""> 4 bytes&gt;</state></pre>	
0x12	0x92	Pulse Beeper		
0x12	0xA4	Reply from main with temperature settings		
0x12	0xBA	Reply from main with encoder settings		
0x12	0xC0	Door Open		0x51 = door open 0x41 = door closed
0x12	0xF2	Temperature to main/dispenser communications test		
0x12	0xF3	Dispenser to main communications test		
0x12	0xF4	Open duct door		
0x12	0xF5	Sweat heater test		
0x12	0xF6	Sensor system self- test		
0v12	OvEO	Forced reset	1	1

# Table 22

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	Thaw 1	Cool	Lock	Filter	Door	Cube	Crush	Water
1	0	0	0	Chill 3	Chill 2	Chill 1	Thaw 3	Thaw 2
2	Bits 0 – 6, Fresh Food LED 0							

## Table 23

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
3	Bits 0 – 6, Fresh Food LED 1							
4	Bits 0 – 6, Fresh Food LED 2							
5	Bits 0 – 6, Freezer LED 0							
6	Bits 0 – 6, Freezer LED 1							
7	Bits 0 – 6, Freezer LED 2							

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Lock	Reset Fresh Filter	Fresh Food Dec	Fresh Food Inc	Freez er Dec	Freez er Inc	Defro st / Chill	Turbo Cool
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	Door	Thaw	Light	Cube Key	Water Key	Crush Key

Table 25

Data Name (Module/Data)	Length	Туре	Function
All Modules / State Code	1	Char	R = Run I = Initialization
Command Processor / Command	1	Structure Pointer	Points to String Where Byte 1 = Command, Byte 2 = Address, Successive Bytes Data
Command Processor / Command (Note: for received commands)	1	Structure Pointer	Points to String Where Byte 1 = Command, Byte 2 = Address, Successive Bytes Data
Dispense / Command	1	Unsigned Char	Bit 0 = Main Valve, Bit 1 = Water Valve, Bit 2 = Electromagnet, Bit 3 = Auger, Bit 4 = Crusher Sol.
Protocol Data Parse / Clr OK	1	Boolean	True Means Clear Buffer False Means Do Not Clear Buffer
Protocol Data Parse / Command & Rstatus	1	Structure Pointer	Points to String Where Boolean = Rstatus (True if command received and CS OK) Byte 1 = Command, Byte 2 = Address, Successive Bytes Data
Protocol Data XMIT / XMIT Status	1	Boolean	True if last command was successfully transmitted. False if last command did not transmit or is still transmitting.

Table 25 continued

Table 35 continued					
Data Name (Module/Data)	Length	Туре	Function		
Protocol Data XMIT / Command	1	String Pointer	Points to String Where Byte 1 = Command, Byte 2 = Address, Successive Bytes Data. NOTE: If pointer is NULL, then XMIT Status is returned based on the success or failure of the previous command.		
LED Control / LED Pattern	1	Unsigned Long	Each of the 32 bits corresponds to an LED.		
Keyboard Scan / Key Status & Key Value	I	Unsigned Int.	MSB = Key Status (1=key pressed) Each of the bits beginning with the LSB correspond to a key. If no key is being pressed the contents of the status will reflect the last key combination pressed.		
Protocol Packet Ready / Rstatus	1	Boolean	True if command received and CS OK Else it returns False		
Physical Xmit Char / Char	1	Unsigned Char	Contains character to be transmitted		
Physical Xmit Char / XMIT Status	1	Boolean	True if last command was successfully transmitted. False if last command did not transmit or is still transmitting.		
Xmit Port Avail / xPort Status	1	Boolean	True if port is available. False if port is not available.		
Key Pressed / Key Status	1	Boolean	True if key is pressed. False if key is not pressed.		

DayCount	4 Bytes - Counts Days for both Filter Functions
OneMinute	1 Byte - Set to 60 when initialized. At 0 one minute has passed.
RXBuffer	16 Bytes - Buffer used to store communication data
Turbo Timer	Unsigned Int – Contains the number of minutes remaining until Turbo Mode times out.
Chill Timer	Unsigned Int – Contains the number of minutes remaining until Quick Chill Mode times out.
Daily Rollover	Unsigned Int - Counts minutes each day

Table 27							
Data Name	Length	Туре	Function				
All Modules / State Code	1	Char	R = Run I = Initialization D = Diagnostics				
Protocol Data Parse / Clr OK	1	Boolean	True Means Clear Buffer False Means Do Not Clear Buffer				
Protocol Data Parse / Command & Rstatus	1	Structure Pointer	Points to String Where Boolean = Rstatus (True if command received and CS OK) Byte 1 = Command, Byte 2 = Address, Successive Bytes Data				
Protocol Data XMIT / XMIT Status	1	Boolean	True if last command was successfully transmitted. False if last command did not transmitting.				
Protocol Data XMIT / Command	1	String Pointer	Points to String Where Byte 1 = Command, Byte 2 = Address, Successive Bytes Data. NOTE: If pointer is NULL, then XMIT Status is returned based on the success or failure of the previous command.				
Apply Calibration Constants & Linearize / Sensor #	1	Unsigned Char	Sensor Number range 1- 255 -				
Apply Calibration Constants & Linearize / Value	1	signed Int	Temperature in degrees Fahrenheit Times 100 Range –12700 to +12800.				
Read Sensor / Sensor #	1	Unsigned Char	Sensor Number range 1- 255				
Read Sensor / A/D Cnts	1	Int	A/D Counts for selected sensor.				